At the same time, an LED in the driver blinks and the description of the error will display. The errors details and LED display details are as follows:

Power state	Blowers state	E_LED (red) state	P_LED (green) state	PULSE output	FOLT output
POWER INPUT BEFORE	STOP	Light off ON OFF	Light off ON OFF	Z (Note 1) ON OFF	Z ON OFF
POWER INPUT AFTER	STOP	Light on ON OFF	Light on ON OFF	HI ON OFF	HI ON OFF
	Normal rotation	Light off ON OFF	Light on ON OFF		HI ON OFF
	Axis current detection	repeat flashing 1000ms:ON/100ms:OFF	Light on ON OFF	$\begin{array}{c} \textcircled{1}{50}\text{ms}:\text{HI} \\ \textcircled{2}{50}\text{ms}:\text{LOW} \rightarrow 100\text{ms}:\text{HI} \\ \textcircled{3}{800}\text{ms}:\text{LOW}(\text{Return to }\textcircled{1}) \\ \overset{\text{HI}}{\rule{0mm}{1mm}} \\ \underset{\begin{array}{c} \square \blacksquare $	
	Axis restrait detection	ON	Light on ON OFF	(1)50ms : HI (2)50ms : LOW→100ms : HI(Two times repeat) (3)650ms : LOW(Return to (1)) HI LOW (1) P P P P P P P P	
	Driver abnormal temperature rise detection	repeat flashing 200ms:ON/200ms:OFF 200ms:ON/1000ms:OFF ON OFF	Light on ON OFF	$\begin{array}{c} \textcircled{1}{50}\text{ms}:\text{HI}\\ \textcircled{2}{50}\text{ms}:\text{LOW}\rightarrow100\text{ms}:\text{HI}(\text{Three times repeat})\\ \textcircled{3}{500}\text{ms}:\text{LOW}(\text{Return to }\textcircled{1})\\ \overset{\text{HI}}{1}\\ \underset{\text{Low}}{1}\\ \underset{\textcircled{1}{2}}{2}\\ \underset{\textbf{a}}{3}\\ \end{array}$	LOW ON OFF
	PFC abnormal detection	repeat flashing 400ms:ON/1000ms:OFF	repeat flashing (same left) ON OFF		
	Blower abnormal temperature rise detection (Note 3)	repeat flashing 200ms:ON/200ms:OFF 200ms : ON / 1000ms : OFF ON OFF	repeat flashing (same left) ON OFF		

Note1 : Z = High impedance

Note2 : PULSE output for $0 \sim 180000$ min-1 rotation speed of the blower, square wave of $0 \sim 60$ Hz is output.

Note3 : If you do not connect the connector(SENSOR) after the power is turned on, it becomes the blower abnormal temperature rise detection.



Output frequency[Hz] = rotation[min⁻¹] / 300